

IN THE SPECIFICATION:

Please replace Page 11 in the application with the following:
(Fig. 10).

A decoy 32 is coupled at each corner 43, 45, 47 and 49, respectively. In one embodiment, a protruding ring at each corner 43, 45, 47 and 49 permits the attachment of guidelines 35. In another exemplary embodiment, a pair of spaced-apart holes in each corner 43, 45, 47 and 49 piece permit the guideline to be inserted therethrough and coupled thereto. In another exemplary embodiment, the collar 41 has pivoting legs 51, 53, 55 and 57 to which each decoy 32 is attached.

In one exemplary embodiment, the side walls 42, 44, 46, and 48 are individual pieces of metal that are welded at the corners 43, 45, 47, and 49, respectively. In another contemplated embodiment, the side walls are formed from a unitary piece that is bent at three corners 43, 45, and 47 and then welded at corner 49. The holes through which guideline 38 passes may be punched in plates at the corners 43, 45, 47, and 49 or actually drilled into the respective side walls adjacent each corner.

When the suspending decoys 30 are secured to the frame 40, the frame 40 can float beneath the water surface 24. The frame 40 supports the motive system 60 via bracket 50.

Support bracket 50 comprises an elongated spar 52 spanning respective side walls 42 and 46. A trunnion 54 upon side wall 48 and a trunnion 56 upon spar 52 permit pivotal movement of the motive system 60. Respective set screws 55 and 57 secure the motive system 60 in the desired orientation. The set screws 55 and 57 permit the user to pivot the motor 60 between a storage or transport position and a deployed position.

Motive system Motor 60 provides the motion to animate the suspending decoys 30 as well as adjacent decoys 34, as will be more thoroughly discussed hereinafter. The motive system motor 60 includes an engine 62 with an attached propeller 64. The engine 62 may be controlled by a remote control 66 attached via